

Structure of the wavefunction array

1 The MCTDH wavefunction

The standard MCTDH wavefunction can be written either in the multi-set

$$\Psi(\mathbf{q}, t) = \sum_{s=1}^{n_s} \sum_{j_1^s \dots j_f^s}^N A_{j_1^s \dots j_f^s}(t) \varphi_{j_1^s}^{(\kappa)}(q_1, t) \cdots \varphi_{j_f^s}^{(\kappa)}(q_f, t)$$

or single-set formalism

$$\Psi(\mathbf{q}, t) = \sum_{j_1 \dots j_f, s}^N A_{j_1 \dots j_f, s}(t) \varphi_{j_1}^{(\kappa)}(q_1) \cdots \varphi_{j_f}^{(\kappa)}(q_f) |s\rangle$$

In Quantics the wavefunction is stored in the `psi` array and the different parts accessed by pointers. How the pointers can be used to unfold the wavefunction is shown in Fig. 1. The Analyse programs `rdacoeff` and `rdspfs` can be used to extract and write the A-coefficients and SPFs to ascii files. The structure of this data is described below.

1.1 The A-vector

The A-coefficients are stored as a vector, or in the multi-set formalism a set of vectors. The vector indices, J ,

$$A_J = A_{j_1 \dots j_f}$$

are a multi-index that can be related to the mode indices by raising the mode indices in sequence. The program `rdacoeff` simply writes the vector and the multi-index J .

As an example, for a 3D system that has 3 SPFs for each mode, there are 27 configurations and the indices are related as shown in Table 1

Table 1: The A-vector indices for a 3D system with 3 SPFs per mode

vector index	Mode indices			vector index	Mode indices			vector index	Mode indices		
J	j_1	j_2	j_3	J	j_1	j_2	j_3	J	j_1	j_2	j_3
1	1	1	1	10	1	1	2	19	1	1	3
2	2	1	1	11	2	1	2	20	2	1	3
3	3	1	1	12	3	1	2	21	3	1	3
4	1	2	1	13	1	2	2	22	1	2	3
5	2	2	1	14	2	2	2	23	2	2	3
6	3	2	1	15	3	2	2	24	3	2	3
7	1	3	1	16	1	3	2	25	1	3	3
8	2	3	1	17	2	3	2	26	2	3	3
9	3	3	1	18	3	3	2	27	3	3	3

To access the indices for a single mode, the vector can be re-shaped as a 3-dimensional tensor with the first index running over a multi-index of all the

preceding modes, the middle index the indices of the mode of interest, and the final index the multi-index for all the following modes.

As an example, for a 4D system with 3 SPFs per mode, the A-vector can be re-shaped around the 3rd mode

$$A_J \longrightarrow A_{J_v j_3 J_n} \Rightarrow \text{Avector}(J_v, j_3, J_n)$$

where in this case the final index runs over the indices of the fourth mode, $J_n = j_4$ and there are 9 indices for the first dimension as listed in Table 2

Table 2: The A-vector indices for the combined 2D first index of a 4D system with 3 SPFs per mode

vector index	Mode indices	
J	j_1	j_2
1	1	1
2	2	1
3	3	1
4	1	2
5	2	2
6	3	2
7	1	3
8	2	3
9	3	3

1.2 The SPFs

The single-particle functions are defined as a vector on the underlying DVR grid for each function. Thus they are stored as matrices

$$\varphi_i(q, t) \longrightarrow \varphi_i(q_\alpha, t) \Rightarrow \text{SPF}(\alpha, i)$$

where the index α runs over the grid points and i over the functions. For a multi-set wavefunction there are n_s sets of functions. The program `rdspfs` writes the sets of functions as vectors.

In a Quantics calculation, if the grid is a DVR then integrals of potential functions are evaluated using a quadrature formalism (see Beck et al Phys. Rep. (2000) 324:1 for details)

$$\langle \varphi_i | h | \varphi_j \rangle = \sum_{\alpha} w_{\alpha} \varphi_i(q_{\alpha}) h(q_{\alpha}) \varphi_j(q_{\alpha})$$

i.e. summing over the value of the SPFs and operator at the DVR grid points.

For ease of manipulation, the SPFs are stored multiplied by the (square-root) of the DVR weights

$$\text{SPF}(\alpha, i) = \sqrt{w_{\alpha}} \varphi_i(q_{\alpha})$$

The program `rdspfs` by default will write out these weighted values. Non-weighted values can be obtained with the option `-nw`.

If there is an electronic DOF, then in a multi-set formalism the SPFs for different states are not orthonormal. For a single-set wavefunction there will also be a set of SPFs for the electronic basis. These are vectors relating an SPF to an electronic state.

2 The G-MCTDH wavefunction

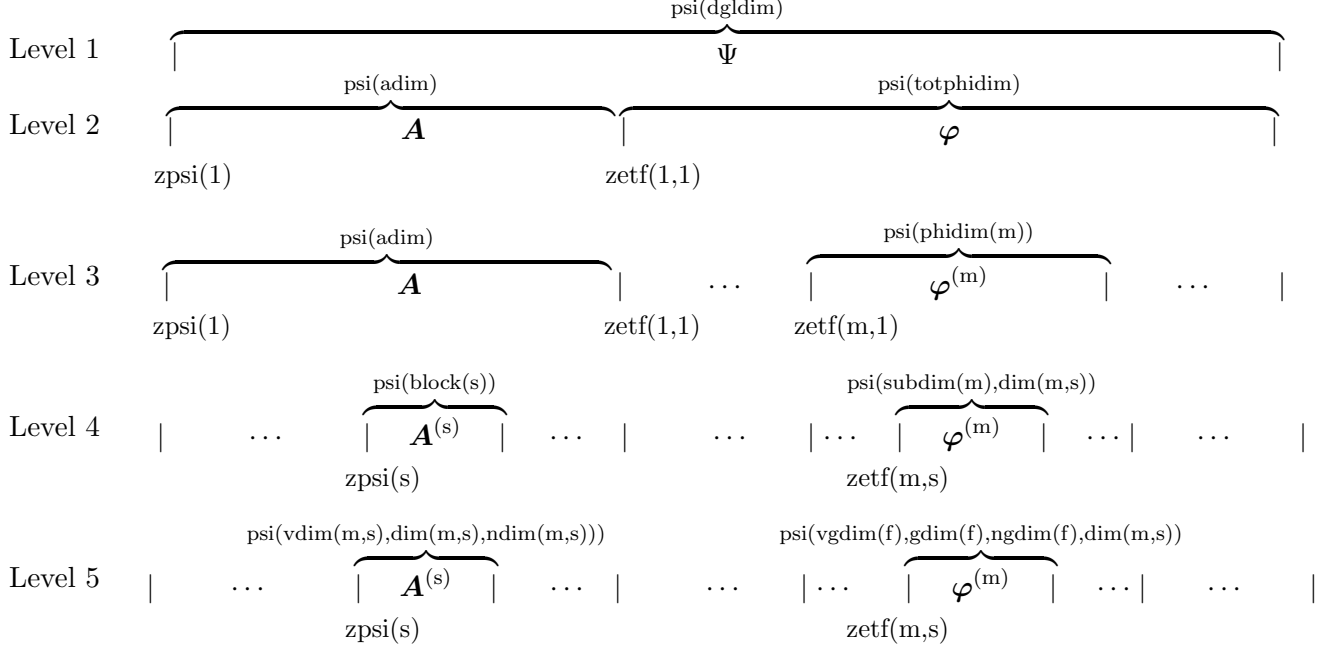
In G-MCTDH wavefunction some or all of the SPFs may be replaced by Gaussian basis functions (GBFs). I.e. in a multi-set function

$$\Psi(\mathbf{q}, t) = \sum_{s=1}^{n_s} \sum_{j_1^s \dots j_f^s}^N A_{j_1^s \dots j_f^s}(t) \varphi_{j_1^s}^{(\kappa)}(q_1, t) \cdots \varphi_{j_n^s}^{(\kappa)}(q_n, t) g_{j_{n+1}^s}^{(\kappa)}(q_{n+1}, t) \cdots g_{j_f^s}^{(\kappa)}(q_f, t)$$

The A-coefficients and SPFs are stored as in a standard MCTDH function. The A-coefficients vector, however, is no longer normalised. The GBFs have the form

$$g_i = \sum_{\alpha\beta} = \zeta_{i,\alpha\beta} x_\alpha x_\beta + \xi_{i,\alpha} x_\alpha + \eta_i$$

and the parameters ζ, ξ, η and written out by `rdspfs`.



- Level 1. The whole wavefunction is stored in the array “psi” which has a length “dglDIM”.
- Level 2. The A coefficient vector has length “adim” starting from the pointer “zpsi(1)”. The SPFs are stored in memory of length “totphidim” starting at “zetf(1,1)”
- Level 3. The SPFs for mode m are stored in memory of length “phidim(m)” starting at “zetf(m,1)”
- Level 4. The A coefficient vector for state s has length “block(s)” starting from the pointer “zpsi(s)”. The SPFs for mode m and state s are a matrix of dimensions “subdim(m) \times dim(m,s)” starting at “zetf(m,s)”
- Level 5. Finally, the A coefficient vector can be reshaped to use the indices for the SPF of mode / state m, s as a tensor with dimensions “vdim(m,s) \times dim(m,s) \times ndim(m,s). The SPF grids can likewise be broken down to index for the DOF f by reshaping “subdim(m) \times dim(m,s)” to “vgdim(f) \times gdim(f) \times ngdim(f) \times dim(m,s)”.

Figure 1: The pointer structure of the psi array